

Reply: Real Business Cycles in Small Open Economy

(Mendoza, 1991)

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1 Model

1.1 Production Technology and Financial Structure.

$$G(K_t, L_t, K_{t+1}) = \exp(e_t) K_t^\alpha L_t^{1-\alpha} - \left(\frac{\phi}{2}\right) (K_{t+1} - K_t)^2, \quad 0 < \alpha < 1, \phi > 0, \quad (1)$$

$$K_{t+1} = (1 - \delta) K_t + I_t, \quad 0 \leq \delta \leq 1, \quad (2)$$

$$A_{t+1} = \text{TB}_t + A_t [1 + r^* \exp(n_t)], \quad (3)$$

$$C_t + I_t + \text{TB}_t \leq \exp(e_t) K_t^\alpha L_t^{1-\alpha} - \left(\frac{\phi}{2}\right) (K_{t+1} - K_t)^2. \quad (4)$$

1.2 Preferences.

$$\mathbb{E}_t \sum_{s=t}^{\infty} \left\{ u(C_s, L_s) \times \exp \left[- \sum_{\tau=t}^{s-1} \nu(C_\tau, L_\tau) \right] \right\}, \quad (5)$$

$$u(C_t, L_t) = \frac{\left(C_t - \frac{L_t^\omega}{\omega}\right)^{1-\gamma} - 1}{1-\gamma}, \quad \omega > 1, \gamma > 1, \quad (6)$$

$$\nu(C_t, L_t) = \beta \ln \left(1 + C_t - \frac{L_t^\omega}{\omega} \right), \quad \beta > 0. \quad (7)$$

1.3 Solution and First Order Conditions.

Let, Θ_t as follows,

$$\Theta_s = \exp \left[- \sum_{\tau=t}^{s-1} \nu(C_\tau, L_\tau) \right] = \prod_{\tau=t}^{s-1} \exp[-\nu(C_\tau, L_\tau)], \quad (8)$$

$$\Theta_s = \exp[-\nu(C_{s-1}, L_{s-1})] \Theta_{s-1}. \quad (9)$$

The Lagrangian associated with the maximization problem is,

$$\max_{\{A_{t+1}, C_t, K_{t+1}, L_t\}} \mathcal{L} = \mathbb{E}_t \sum_{s=t}^{\infty} \Theta_s \left\{ u_s + \lambda_s (G_s - C_s - I_s - \text{TB}_s) + \mu_s \left[\frac{\Theta_{s+1}}{\Theta_s} - \exp(-\nu_s) \right] \right\}, \quad (10)$$

$$\frac{\partial \mathcal{L}}{\partial A_{t+1}} : -\Theta_t \lambda_t \frac{\partial \text{TB}_t}{\partial A_{t+1}} - \text{E}_t \left(\Theta_{t+1} \lambda_{t+1} \frac{\partial \text{TB}_{t+1}}{\partial A_{t+1}} \right) = 0, \quad (11)$$

$$\frac{\partial \mathcal{L}}{\partial C_t} = \Theta_t \left[\frac{\partial u_t}{\partial C_t} - \lambda_t + \mu_t \exp(-\nu_t) \frac{\partial \nu_t}{\partial C_t} \right] = 0, \quad (12)$$

$$\frac{\partial \mathcal{L}}{\partial K_{t+1}} : \Theta_t \lambda_t \left(\frac{\partial G_t}{\partial K_{t+1}} - \frac{\partial I_t}{\partial K_{t+1}} \right) + \text{E}_t \left[\Theta_{t+1} \lambda_{t+1} \left(\frac{\partial G_{t+1}}{\partial K_{t+1}} - \frac{\partial I_{t+1}}{\partial K_{t+1}} \right) \right] = 0, \quad (13)$$

$$\frac{\partial \mathcal{L}}{\partial L_t} : \Theta_t \left[\frac{\partial u_t}{\partial L_t} + \lambda_t \frac{\partial G_t}{\partial L_t} + \mu_t \exp(-\nu_t) \frac{\partial \nu_t}{\partial L_t} \right] = 0, \quad (14)$$

$$\frac{\partial \mathcal{L}}{\partial \Theta_{t+1}} : \mu_t + \text{E}_t \{ u_{t+1} + \lambda_{t+1} [G_{t+1} - C_{t+1} - I_{t+1} - \text{TB}_{t+1}] - \mu_{t+1} \exp(-\nu_{t+1}) \} = 0,$$

$$\frac{\partial \mathcal{L}}{\partial \lambda_t} : \Theta_t (G_t - C_t - I_t - \text{TB}_t) = 0, \quad (15)$$

$$\frac{\partial \mathcal{L}}{\partial \mu_t} : \Theta_t \left[\frac{\Theta_{t+1}}{\Theta_t} - \exp(-\nu_t) \right] = 0. \quad (16)$$

From equation (16) we can notice that

$$\frac{\Theta_{t+1}}{\Theta_t} = \exp(-\nu_t).$$

$$u_{c,t} \equiv \frac{\partial u_t}{\partial C_t} = \left(C_t - \frac{L_t^\omega}{\omega} \right)^{-\gamma},$$

$$u_{l,t} \equiv \frac{\partial u_t}{\partial L_t} = -L_t^{\omega-1} u_{c,t}$$

$$\nu_{c,t} \equiv \frac{\partial \nu_t}{\partial C_t} = \beta \left(1 + C_t - \frac{L_t^\omega}{\omega} \right)^{-1}, \quad (17)$$

$$\nu_{l,t} \equiv \frac{\partial \nu_t}{\partial L_t} = -L_t^{\omega-1} \frac{\partial \nu_t}{\partial C_t}. \quad (18)$$

Replacing the functional forms we have the following FOCs

$$\lambda_t = \text{E}_t \{ \exp(-\nu_t) [1 + r^* \exp(n_t)] \lambda_{t+1} \}, \quad (19)$$

$$\lambda_t = u_{c,t} + \mu_t \exp(-\nu_t) \nu_{c,t} \quad (20)$$

$$\lambda_t [\phi (K_{t+1} - K_t) + 1] = \text{E}_t \left\{ \exp(-\nu_t) \left[\alpha \exp(e_{t+1}) \left(\frac{L_{t+1}}{K_{t+1}} \right)^{1-\alpha} + 1 - \delta \right] \lambda_{t+1} \right\}, \quad (21)$$

$$L_t = [(1 - \alpha) \exp(e_t) K_t^\alpha]^{\frac{1}{\omega + \alpha - 1}}, \quad (22)$$

$$\mu_t = \text{E}_t [\mu_{t+1} \exp(-\nu_{t+1}) - u_{t+1}], \quad (23)$$

$$G_t = C_t + I_t + \text{TB}_t. \quad (24)$$

1.4 Steady-State

$$L = \left[(1 - \alpha) \left(\frac{\alpha}{r^* + \delta} \right)^{\frac{\alpha}{1-\alpha}} \right]^{\frac{1}{\omega-1}}.$$

$$K = \left(\frac{\alpha}{r^* + \delta} \right)^{\frac{1}{1-\alpha}} L,$$

$$G = K^\alpha L^{1-\alpha},$$

$$I = \delta K,$$

$$C = (1 + r^*)^{1/\beta} + \frac{L^\omega}{\omega} - 1,$$

$$\text{TB} = G - C - I,$$

$$A = -\frac{\text{TB}}{r^*}$$

$$\lambda = u_c + \mu \exp(-\nu) \nu_c,$$

$$\mu = -\left(\frac{1 + r^*}{r^*} \right) u,$$