

2-country NK model

$$\beta_i \frac{R_{i,t}}{E_t(\pi_{i,t+1})} = \frac{(C_{i,t}(j) - h_i C_{i,t-1}(j))^{-\sigma_{C_i}} - \beta_i h_i (E_t(C_{i,t+1}(j)) - C_t(j) h_i)^{-\sigma_{C_i}}}{(E_t(C_{i,t+1}(j)) - h_i C_{i,t}(j))^{-\sigma_{C_i}} - \beta_i h_i (E_t(C_{i,t+2}(j)) - E_t(C_{t+1}(j)) h_i)^{-\sigma_{C_i}}} \quad (1)$$

$$\chi_{b_i} (H_{i,t}(j))^{\sigma_{L_i}} = (C_{i,t}(j) - h_i C_{i,t-1}(j))^{-\sigma_{C_i}} - \beta_i h_i (E_t(C_{i,t+1}(j)) - C_t(j) h_i)^{-\sigma_{C_i}} w_{i,t} \quad (2)$$

$$q_{i,t} = \frac{1}{a_1} \left(\frac{I_{i,t}}{K_{i,t-1}} \right)^{a_3} \quad (3)$$

$$q_{i,t} \frac{R_{i,t}}{E_t(\pi_{i,t+1})} = \left\{ z_{i,t+1} + E_t q_{t+1} \left(1 - \delta + \frac{a_1}{1 - a_3} \left(\frac{I_{i,t}}{K_{i,t-1}} \right)^{1 - a_3} + a_2 - a_1 \left(\frac{I_{i,t}}{K_{i,t-1}} \right)^{1 - a_3} \right) \right\} \quad (4)$$

$$E_t \begin{bmatrix} e_{i,t+1} \\ e_{i,t} \end{bmatrix} = \frac{R_{i,t}}{R_{j,t}} (1 + \chi_{b_i} e_{i,t} b_{i,t}^j(j)) \quad (5)$$

$$K_{i,t}(j) = (1 - \delta) K_{i,t-1}(j) + \left(\frac{a_1}{1 - a_3} \left(\frac{I_{i,t}}{K_{i,t-1}} \right)^{1 - a_3} + a_2 \right) \cdot K_{i,t-1}(j) \quad (6)$$

$$X_{i,t}(z) = \frac{A_{i,t} K_{i,t-1}(z)^\alpha H_{i,t}(z)^{1 - \alpha}}{v_{i,t}} \quad (7)$$

$$(1 - \alpha) z_{i,t} K_{i,t-1}(z) = \alpha w_{i,t} H_{i,t}(z) \quad (8)$$

$$m c_{i,t}(z) = \frac{1}{A_{i,t}} \left(\frac{z_{i,t}}{\alpha} \right)^\alpha \left(\frac{w_{i,t}}{1 - \alpha} \right)^{1 - \alpha} \quad (9)$$

$$1 = (1 - \Xi) [(\pi_{i,t}^x)(\pi_{i,t}^{-1})]^{1 - \psi} + (\Xi) [(RER_{i,t})(\pi_{j,t}^x)(\pi_{j,t}^{-1})]^{1 - \psi} \quad (10)$$

$$x_{1,t} = \lambda_{i,t}^c \cdot m c_{i,t} \cdot X_{i,t} + \theta \beta E(\pi_{i,t+1})^{\frac{\mu_{i,t}}{\mu_{i,t} - 1}} \cdot x_{1,t+1} \quad (11)$$

$$x_{2,t} = \lambda_{i,t}^c \cdot X_{i,t} + \theta \beta E(\pi_{i,t+1})^{-\frac{1}{\mu_{i,t} - 1}} \cdot x_{2,t+1} \quad (12)$$

$$\pi_{i,t}^x = \mu_{i,t} \cdot \pi_{i,t} \cdot \frac{x_{1,t}}{x_{2,t}} \quad (13)$$

$$v_{i,t}^P = (1 - \theta) (\pi_{i,t}^x)^{-\frac{\mu_{i,t}}{\mu_{i,t} - 1}} (\pi_{i,t})^{\frac{\mu_{i,t}}{\mu_{i,t} - 1}} + (\pi_{i,t})^{\frac{\mu_{i,t}}{\mu_{i,t} - 1}} \cdot \theta \cdot v_{i,t-1}^P \quad (14)$$

$$X_{i,t} = \left[(1 - \Xi) [(\pi_{i,t}^x)(\pi_{i,t}^{-1})]^{-\psi} \right] \cdot Y_{i,t} \cdot v_{i,t}^P + \left[(\Xi) \left[\frac{1}{RER_{i,t}} (\pi_{j,t}^x)(\pi_{j,t}^{-1}) \right]^{-\psi} \right] \cdot Y_{j,t} \cdot v_{j,t}^P \quad (15)$$

$$C A_{i,t} = b_{i,t}^j - b_{i,t-1}^j \quad (16)$$

$$Y_{i,t} = C_{i,t} + I_{i,t} + 0.5 \chi_{b_i} e_{i,t} b_{i,t}^j(j) \quad (17)$$

$$\log \left(\frac{R_{i,t}}{R_{i,SS}} \right) = \rho \cdot \log \left(\frac{R_{i,t-1}}{R_{i,SS}} \right) + (1 - \rho) \cdot \phi_\pi \cdot \log \left(\frac{\pi_{i,t}}{\pi_{i,SS}} \right) \quad (18)$$

$$\frac{RER_{i,t}}{RER_{i,t-1}} = \frac{\pi_{j,t}}{\pi_{i,t}} \frac{e_{i,t}}{e_{i,t-1}} \quad (19)$$

$$b_{h,t}^f = \frac{e_t}{e_{t-1}} \frac{R_{f,t-1}}{\pi_{i,t}} b_{h,t-1}^f + (\pi_{i,t}^x \cdot \pi_{i,t}^{-1}) (X_{i,t} - Y_{i,t}) \quad (20)$$

$$A_{i,t} = (1 - \rho_A) \cdot A_{i,SS} + \rho_A \cdot A_{i,t-1} + \epsilon_{i,t}^A \quad \text{with} \quad \epsilon_{i,t}^A \sim N(0, \sigma_A^2) \quad (21)$$